



Robotic Guitar Interface Device-Rehabilitation and Research Guitar Bot (RRGB)
Team #1 - Zachary Brandon, Michael Bryant, Alexander Douglas, Matthew Haase, Kevin Justice, James Kirsch, and Nicholas Miller

Objective Statement

The RRGB will be designed primarily as a research apparatus for the Louisiana State University Kinesiology Department that will enable stroke victims to undergo an experimental rehabilitation technique that combines rhythmic and discrete movements while playing guitar.

Engineering Specifications

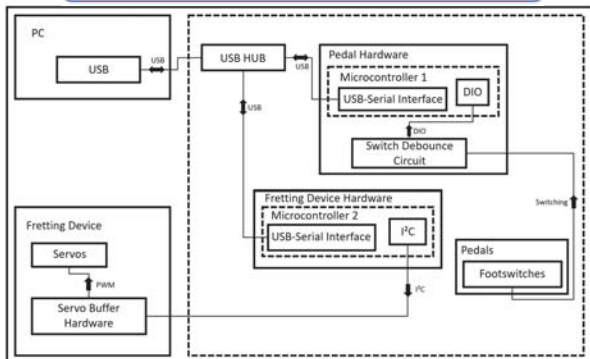
Functions:

- Actuates chords on first four frets of guitar
- Foot pedal controls
- Computer-Based user interface for device configuration
- Scrolling Timing Indicator on Computer Interface

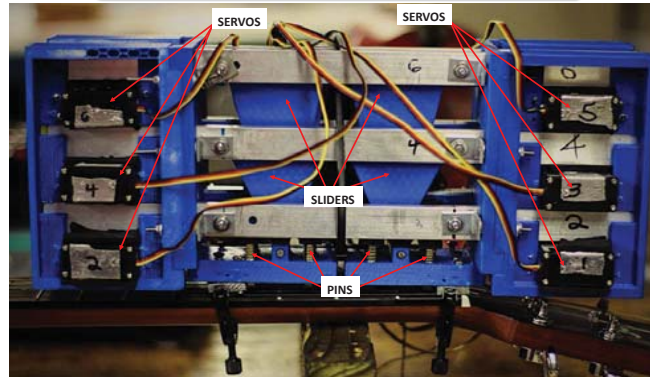
Constraints/Measurable Specifications:

- Attachable/Detachable
- PC compatible user interface
- Two modes of operation
- Four foot pedals
- Less than 500ms actuation delay

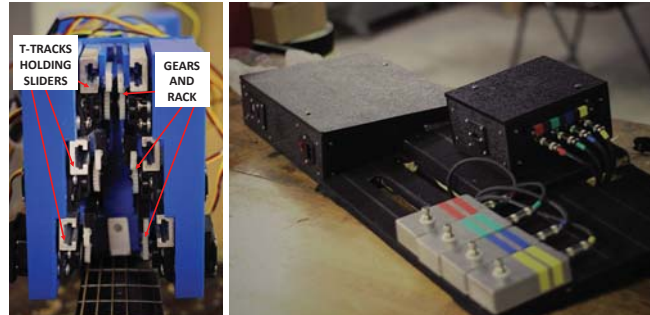
Electronic Hardware Schematic



Prototype

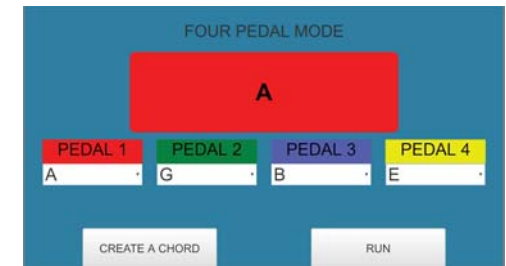


Side view of fretting device without enclosure (Forms chord shapes)



Back view of fretting device (left). Power supply along with pedals and pedal board (right).

User Interface and Pedal Board



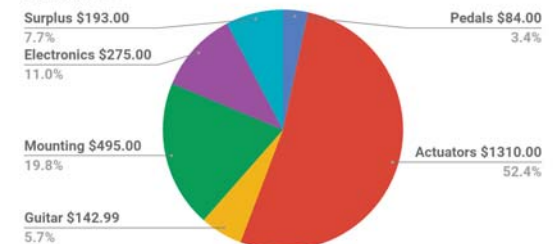
Four Pedal Mode page from the User Interface.



Device pedal hardware (Controls Actuation of Chords)

Budget

Total: \$2500



Safety Considerations

- Moving and electrical components will be enclosed to prevent injury
- All electronics will be capable of handling currents that meet or exceed the range required for normal operation of the device.

